## 9. Conformal Mapping

Definition 9.1. A circline is a circle or a line in the complex plane.
Definition 9.2. The Riemann sphere is the complex plane $\mathbf{C}$ with one extra point added (the "point at infinity"). We can think of this as the union of two copies of $\mathbf{C}$, with one of them parametrized by $z$ and the other by $w$ with the convention

$$
z w=1
$$

leading to $z=0$ iff $w=\infty$ and $w=0$ iff $z=\infty$.
Definition 9.3. (inverse points) $\alpha$ and $\beta$ are inverse points w.r.t. the circle $|z-a|=r$ if

$$
(\alpha-a)(\bar{\beta}-\bar{\alpha})=r^{2}
$$

$\alpha$ and $\beta$ are inverse with respect to a straight line $\ell$ if $\beta$ is the reflection of $\alpha$ in $\ell$.
Remark 9.4. Given a pair of points and a third point, there is exactly one circline for which the pair of points are inverse points with respect to the circline and the third point is in the circline.

### 9.1. Conformal Mapping.

Theorem 9.5. If $f$ is holomorphic in an open set $G$ and $f^{\prime}(z) \neq 0$ for some $z \in G$, then $f$ preserves angles between lines meeting at $z$.
Definition 9.6. A mapping $f$ is conformal in an open set $G$ if $f$ is holomorphic on $G$ and $f^{\prime}(z) \neq 0$ for any $z \in G . f$ is conformal at a point $w$ if it is conformal on some small disc containing $w$.

A conformal mapping preserves the sign of angles as well as their size. If $f^{\prime}(z)=0$, then $f$ does not preserve angles at $z$. For example the map $f(z)=z^{2}$ doubles the angles at $z=0$.
9.2. Construction of conformal maps. If we want a conformal map to send the upper half plane $H=\mid\{x+i y \mid y>0\}$ onto the open unit disc $D(0 ; 1)$, we require that f is conformal on $H$ and $f$ sends the line $\{x+i y \mid y=0\}$ to the circle $|z|=1$. This is accomplished by a linear fractional transformation or Möbius transformation

$$
f(z)=\frac{a z+b}{c z+d}
$$

. We find

$$
f(z)=\frac{z-i}{z+i}
$$

since it is easy to see that this map sends the real axis to the unit circle.

Remark 9.7. If $f$ and $g$ are conformal maps, then so is $f \circ g$.
Theorem 9.8. If $\left\{z_{1}, z_{2}, z_{3}\right\}$ and $\left\{w_{1}, w_{2}, w_{3}\right\}$ are in $\mathbf{C}$ and $z_{1} \neq z_{2} \neq$ $z_{3}, w_{1} \neq w_{2} \neq w_{3}$. Then there is a unique Möbius transformation taking $z_{j}$ to $w_{j}$ for all $j=1,2,3$.

So to find a conformal map taking one circline to another, we just have to solve the equation for the map to send three specified points to three other specified points.
(A line is a special case of a circline, since all lines contain the point at infinity. For any two points in the complex plane there is only one line passing through both of them.)

The procedure to find a conformal map taking one region to another is to identify such a conformal map as the composition of a number of conformal maps using a table showing some standard conformal maps and the image of the unit circle under these maps.

### 9.3. Harmonic functions.

Definition 9.9. A real-valued function $u(x, y)$ is harmonic if
(1) The partial derivatives of $u$ are continuous, and

$$
\begin{equation*}
u_{x x}+u_{y y}=0 \tag{2}
\end{equation*}
$$

Theorem 9.10. If $f=u+i v$ is holomorphic, then $u$ is harmonic.
9.3.1. Harmonic conjugates. If $u(x, y)$ is harmonic, then there is a harmonic conjugate $v$ for which $u+i v$ is holomorphic. This means $u$ and $v$ satisfy the Cauchy-Riemann equations. To find the harmonic conjugate, we solve the Cauchy-Riemann equations for $v$.

Example 9.1. Let $u(x, y)=2 x y$. Then

$$
u_{x}=2 y .
$$

Using the Cauchy-Riemann equations,

$$
v_{y}=2 y
$$

so

$$
v(x, y)=y^{2}+h(x)
$$

Now differentiate $v$ with respect to $x$ :

$$
v_{x}=\frac{d h}{d x}
$$

Now impose the Cauchy-Riemann equation:

$$
\left(v_{x}=\right)-u_{y}=\frac{d h}{d x}
$$

Now differentiate $u$ with respect to $y$ :

$$
u_{y}=2 x
$$

so we have

$$
\frac{d h}{d x}=-2 x
$$

and $h=-x^{2}+C$ where $C$ is a constant. It follow that the harmonic conjugate is

$$
v=y^{2}-x^{2}+C
$$

Notice that $-v$ (respectively $u$ ) are the real (respectively imaginary) parts of $f(z)=z^{2}$.

### 9.4. Conformal maps sending the upper half plane to the unit

disk. If $f$ sends the upper half plane to the unit cirle, let

$$
f(z)=\frac{a z+b}{c z+d}
$$

Because $|f(z)|=1$ when $z$ is a real number, we have

$$
\frac{a x+b}{c x+d}=1 .
$$

Taking $x=0$ we have $|b|=|d|$. Taking $x=\infty$ we have $|a|=|c|$. We may assume $a=1$, as long as $a \neq 0$ (divide both the numerator and denominator by $a$ so that $a$ is replaced by 1 ). So we have writing $b=r e^{i \theta}$

$$
f(x)=\frac{x+r e^{i \theta}}{e^{i \psi} x+r e^{i \phi}}
$$

which is on the unit circle. This implies

$$
\left|x+r e^{i \theta}\right|=\left|x+r e^{i(\phi-\psi)}\right|
$$

This implies (taking the square of the absolute value and matching the coefficients of $x$ and $x^{2}$ ) that either

$$
e^{i \theta}=e^{i(\phi-\psi)}
$$

or

$$
e^{i \theta}=e^{-i(\phi-\psi)}
$$

So our map is

$$
f(x)=e^{-i \psi}\left(\frac{x+r e^{i \theta}}{x+r e^{i \theta}}\right)
$$

or

$$
f(x)=e^{-i \psi}\left(\frac{x+r e^{i \theta}}{x+r e^{-i \theta}}\right)
$$

The first map sends the entire real axis to $e^{-i \psi}$ (this is a conformal map, but not the one we want). The second map sends

$$
\begin{equation*}
f(x)=e^{-i \psi}\left(\frac{x+a}{x+\bar{a}}\right) \tag{1}
\end{equation*}
$$

for some real number $\psi$ and some complex number $a$.
The example presented in class

$$
\begin{equation*}
f(z)=\frac{z-i}{z+i} \tag{2}
\end{equation*}
$$

takes the upper half plane to the unit circle, but it is not the only conformal map that takes the upper half plane to the unit circle. (2) is a special case of (1) (taking $\psi=0$ and $a=-i$ ). All other conformal maps taking the upper half plane to the unit circle are obtained by composing with conformal maps $g$ taking $(1,-1, i)$ to general values in the unit circle

$$
\begin{gathered}
g(1)=e^{i C} \\
g(-1)=e^{i A} \\
g(i)=e^{i B}
\end{gathered}
$$

This means

$$
\begin{gathered}
\frac{a+b}{c+d}=e^{i C} \\
\frac{-a+b}{-c+d}=e^{i A} \\
\frac{a+i b}{c+i d}=e^{i B} \\
g(z)=\frac{a z+b}{c z+d}
\end{gathered}
$$

where we set $a=1$ and solve

$$
\begin{gather*}
b-e^{i C} c-e^{i C} d=-1  \tag{3}\\
b+e^{i A} c+e^{i A} d=+1  \tag{4}\\
i b-e^{i B} c-i e^{i B} d=-1 \tag{5}
\end{gather*}
$$

Subtracting (4) from (3)

$$
\binom{c}{d}=\frac{1}{\operatorname{det}(R)} R\binom{-2}{-1+i}
$$

where $R$ is the matrix

$$
R=\left(\begin{array}{cc}
-e^{i C}+i e^{i B} & e^{-i C}+e^{i A} \\
e^{i C}-i e^{i B} & -e^{i C}-e^{i A}
\end{array}\right)
$$

Finally we solve for $b$ using (3).

